

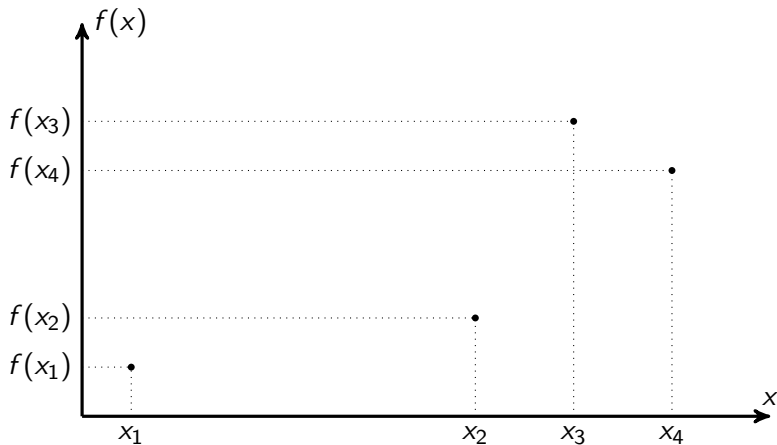
# Parallel Gaussian Process Optimization with Upper Confidence Bound and Pure Exploration

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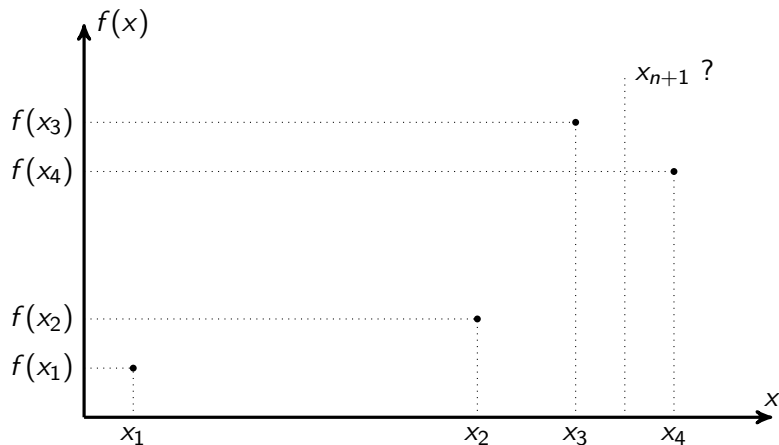
CMLA, ENS Cachan, France

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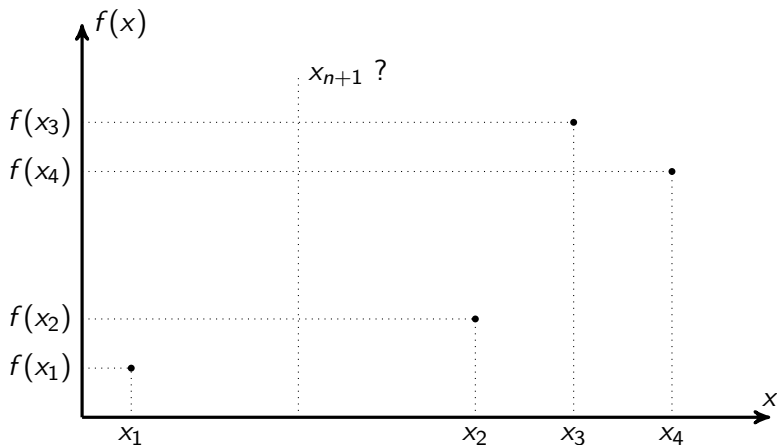
# Motivating example: Sequential optimization



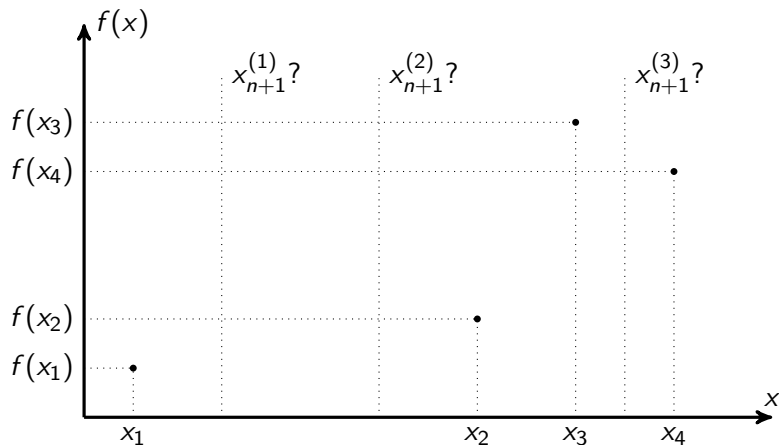
# Motivating example: Sequential optimization



# Motivating example: Sequential optimization



# Motivating example: Batch optimization



# Problem Statement

## Setup

- ▶ Unknown  $f : \mathcal{X} \rightarrow \mathbb{R}$ , where  $\mathcal{X} \in \mathbb{R}^d$  compact and convex
- ▶ Find  $x^* = \operatorname{argmax}_{x \in \mathcal{X}} f(x)$
- ▶ At iteration  $t$ , query a batch of  $K$  locations  $x_t^1, \dots, x_t^K \in \mathcal{X}$
- ▶ Observe the noisy evaluations of  $f$ ,  $y_t^1, \dots, y_t^K \in \mathbb{R}$ ,  
 $y_t^k = f(x_t^k) + \epsilon_t^k$  where  $\epsilon_t^k \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma^2)$

## Examples

- ▶ Heavy numerical experiment on a cluster with  $K$  cores
- ▶ Sensor placement with  $K$  sensors
- ▶ Laboratory experiment, ...

# Bandit setting

## Cumulative regret

- ▶ Exploration / Exploitation

- ▶ Batch cumulative regret:  $R_T^K = \sum_{t=1}^T \left( f(x^*) - \max_{k \leq K} f(x_t^k) \right)$

- ▶ Full cumulative regret:  $R_{TK} = \sum_{t=1}^T \sum_{k=1}^K \left( f(x^*) - f(x_t^k) \right)$

# Gaussian Processes

## Definition

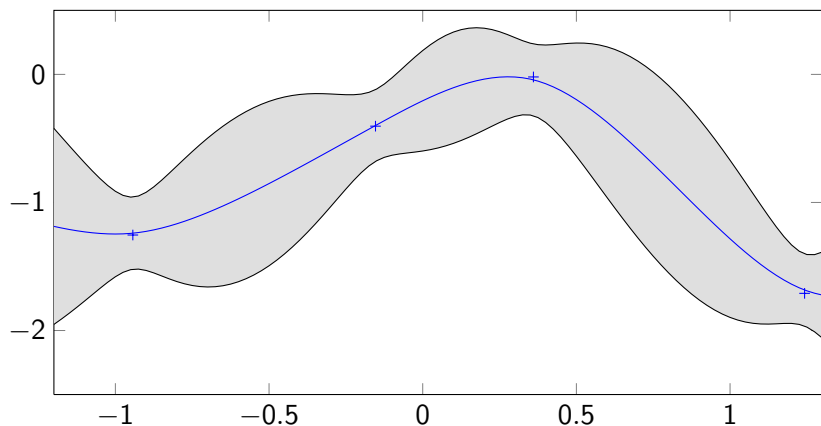
$f \sim \mathcal{GP}(m, k)$ , with **mean** function  $m : \mathcal{X} \rightarrow \mathbb{R}$  and **kernel** function  $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}^+$ , when for all  $x_1, \dots, x_n$  the values  $(f(x_1), \dots, f(x_n))$  are distributed as a **multivariate Gaussian** with mean and variance given by  $m$  and  $k$ .

## Bayesian Inference (Rasmussen and Williams, 2005)

At iteration  $t$ , with observations  $\mathbf{Y}_{X_t}$  at  $X_t = \{x_1^1, \dots, x_t^K\}$ , the posterior distribution  $\Pr[f \mid \mathbf{Y}_{X_t}]$  is a Gaussian process with mean and covariance given by the Bayesian inference. At each point  $x \in \mathcal{X}$ , we can compute a **prediction** with  $\mu_{t+1}(x)$  and **uncertainty** with  $\sigma_{t+1}^2(x)$ .



# Example: Bayesian inference with 4 observations



# Upper and Lower Confidence Bounds

## Definition

Fix  $0 < \delta < 1$ ,

$$f_t^+(x) = \mu_t(x) + \sqrt{\beta_t \sigma_t^2(x)}$$

$$f_t^-(x) = \mu_t(x) - \sqrt{\beta_t \sigma_t^2(x)}$$

with  $\beta_t = \mathcal{O}(\log \frac{t}{\delta})$  defined in Srinivas et al. (2012)

## Property

$$\forall x \in \mathcal{X}, \forall t \geq 1,$$

$f(x) \in [f_t^-(x), f_t^+(x)]$  holds with probability at least  $1 - \delta$

# Relevant Region

## Definition

The Relevant Region  $\mathfrak{R}_t$  and the extended  $\mathfrak{R}_t^+$  are defined by,

$$y_t^\bullet = \max_{x \in \mathcal{X}} f_t^-(x)$$

$$\mathfrak{R}_t = \left\{ x \in \mathcal{X} \mid f_t^+(x) \geq y_t^\bullet \right\}$$

$$\mathfrak{R}_t^+ = \left\{ x \in \mathcal{X} \mid \mu_t(x) + 2\sqrt{\beta_{t+1}\sigma_t^2(x)} \geq y_t^\bullet \right\}$$

## Property

$\operatorname{argmax}_{x \in \mathcal{X}} \hat{f}_{t+1}^+(x) \in \mathfrak{R}_t^+$  with high probability

# UCB and Pure Exploration

## UCB policy

$$x_t^1 \leftarrow \operatorname{argmax}_{x \in \mathfrak{X}_t^+} \widehat{f}_t^+(x)$$

## Pure Exploration policy

$$\text{For } 2 \geq k \geq K, x_t^k \leftarrow \operatorname{argmax}_{x \in \mathfrak{X}_t^+} \sigma_t^{(k)}(x)$$

where  $\sigma_t^{(k)}(x)$  is the updated deviation after having selected  $x_t^1, \dots, x_t^{k-1}$

# GP-UCB-PE

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## Algorithm 1: GP-UCB-PE

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**for**  $t = 1, 2, \dots$  **do**

    Compute  $\mu_t$  and  $\sigma_t^2$  with Bayesian inference on  $y_1^1, \dots, y_{t-1}^K$

    Compute  $\mathfrak{X}_t^+$

$x_t^1 \leftarrow \operatorname{argmax}_{x \in \mathfrak{X}_t^+} \hat{f}_t^+(x)$

**for**  $k = 2, \dots, K$  **do**

        Update  $\sigma_t^{(k)}$

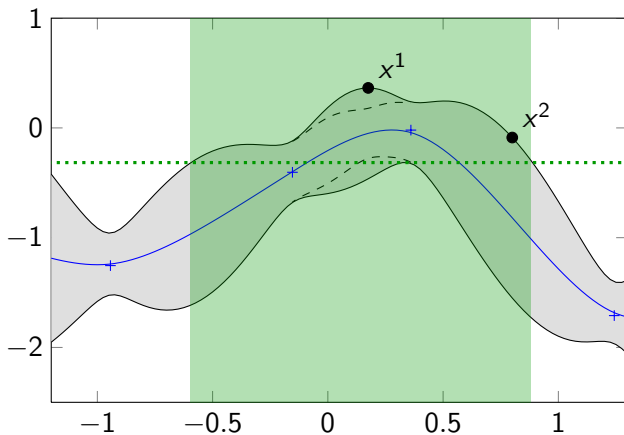
$x_t^k \leftarrow \operatorname{argmax}_{x \in \mathfrak{X}_t^+} \sigma_t^{(k)}(x)$

    Query  $\{x_t^k\}_{1 \leq k \leq K}$

    Observe  $\{y_t^k\}_{1 \leq k \leq K}$

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# Example: GP-UCB-PE



# Regret Bounds

## Theorem

With  $f \sim \mathcal{GP}(0, k)$  and  $k(x, x) \leq 1$ , with high probability:

$$R_T^K = \mathcal{O}\left(\sqrt{\gamma_{TK} \frac{T}{K} \log T}\right)$$

$$\text{and } R_{TK} = \mathcal{O}\left(\sqrt{\gamma_{TK} TK \log T}\right)$$

## Mutual Information

$\gamma_{TK}$  is the maximum mutual information about  $f$  obtainable by a sequence of  $TK$  queries.

- ▶ For linear kernel,  $\gamma_{TK} = \mathcal{O}(d \log TK)$
- ▶ For RBF kernel,  $\gamma_{TK} = \mathcal{O}((\log TK)^{d+1})$

# Corollary

## Corollary (Batch vs Sequential)

*With  $K \ll T$ , the improvement of the parallel strategy over the sequential one is  $\sqrt{K}$  with respect to  $R_T^K$ .*

## Remark (GP-BUCB, Desautels et al. (2012))

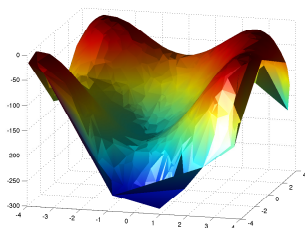
*Compared to GP-BUCB, there is no need for an initialization phase. The improvement can be doubly exponential in the dimension  $d$ .*



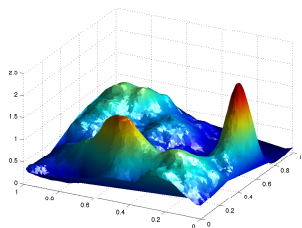
# Experiments

## Setup

- ▶ Competitors: GP-BUCB (Desautels et al. (2012)) and SM+UCB (Azimi et al. (2010))
- ▶ Assessment: 3 synthetic problems and 3 real applications

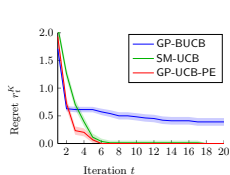


(a) Himmelblau

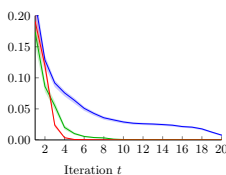


(b) Gaussian Mixture

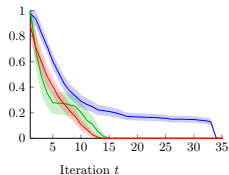
# Results: mean instantaneous batch regret and confidence interval over 64 experiments



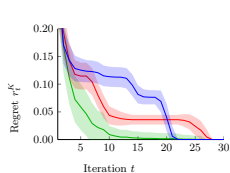
(a) Generated GP



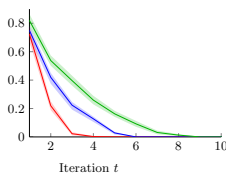
(b) Himmelblau



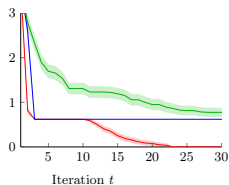
(c) Gaussian mixture



(d) Mackey-Glass



(e) Tsunamis



(f) Abalone

# Conclusion

## GP-UCB-PE

- ▶ Theoretical upper bounds on the cumulative regret
- ▶ Efficient in practice
- ▶ Easy to implement

## Implementation

MATLAB source codes, documentation and data sets are available at <http://econtal.perso.math.cnrs.fr/software/>.

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- Srinivas, N., Krause, A., Kakade, S. M., and Seeger, M. W. (2012). Information-theoretic regret bounds for gaussian process optimization in the bandit setting. *IEEE Transactions on Information Theory*, 58(5):3250–3265.